

Convolutional NNs and Generative Models

Friday
08h00-09h00

Géraldine Conti, Matthew Vowels, Mykhailo Vladymyrov
Bern Winter School on Machine Learning 2024, Mürren

TO COMPLETE YOUR REGISTRATION, PLEASE TELL US
WHETHER OR NOT THIS IMAGE CONTAINS A STOP SIGN:



NO YES

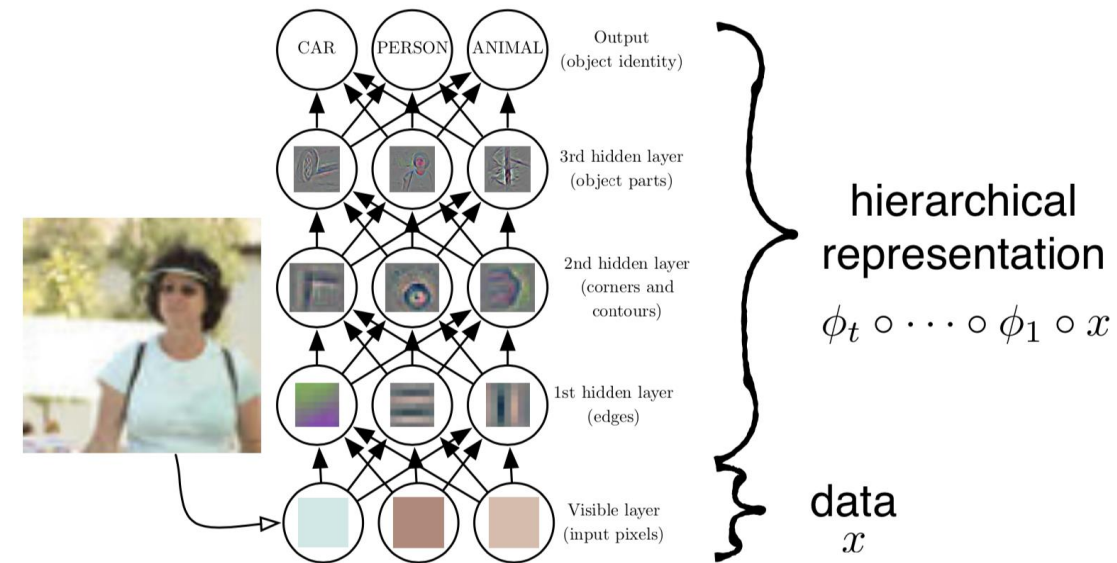
ANSWER QUICKLY—OUR SELF-DRIVING
CAR IS ALMOST AT THE INTERSECTION.

SO MUCH OF "AI" IS JUST FIGURING OUT WAYS
TO OFFLOAD WORK ONTO RANDOM STRANGERS.

Convolutional Neural Networks

- Specialized Neural Network for data arranged **on a continuous grid**
 - Images, signal waveform samples, ...
 - DNA sequences
 - ...

	A	C	G	T	W	S	M	K	R	Y	B	D	H	V	N	Z
A	1	0	0	0	1/2	0	1/2	0	1/2	0	0	1/3	1/3	1/3	1/4	0
C	0	1	0	0	0	1/2	1/2	0	0	1/2	1/3	0	1/3	1/3	1/4	0
G	0	0	1	0	0	1/2	0	1/2	1/2	0	1/3	1/3	0	1/3	1/4	0
T	0	0	0	1	1/2	0	0	1/2	0	1/2	1/3	1/3	1/3	0	1/4	0



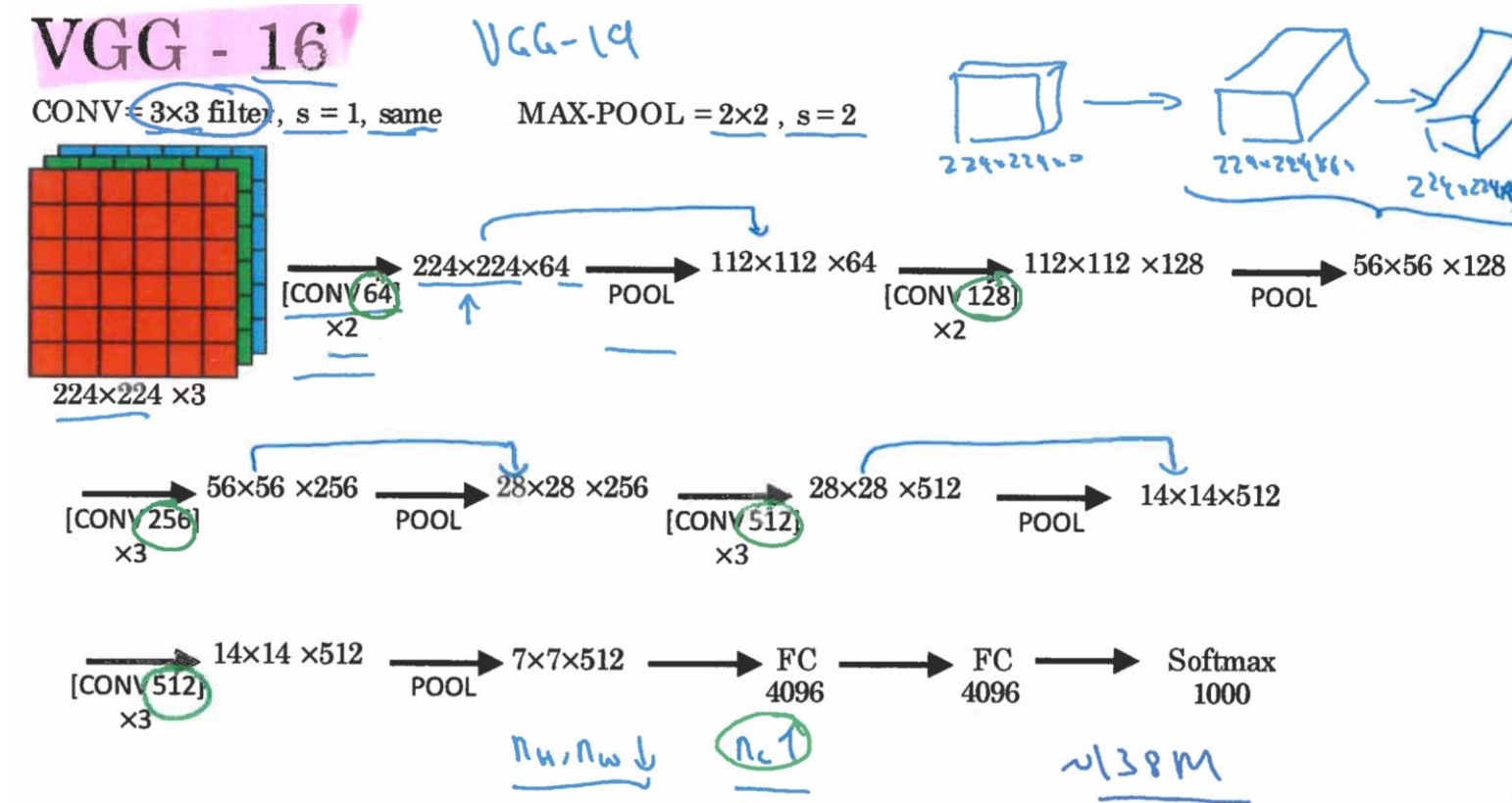
Types of layer in CNN

- Convolution (CONV)

- Pooling (POOL)

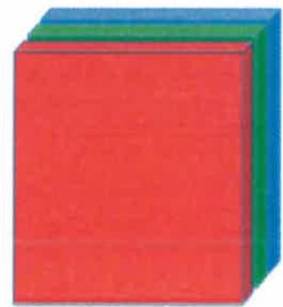
- Fully connected (FC)

- Usually multiple CONV layers followed by a POOL layer, and FC layers in the last few layers

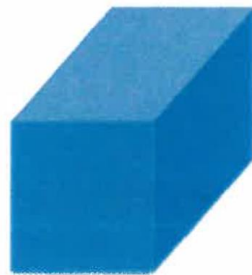


Convolution Layer (CONV)

- **Convolution** transforms an input volume into an **output volume** of different size, also called **feature map**
- **Filter kernels** are used to detect features (for example, edge detection in 1st hidden layer)



Input volume



Output volume

10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0



0	0	0	10	10	10
0	0	0	10	10	10
0	0	0	10	10	10
0	0	0	10	10	10
0	0	0	10	10	10
0	0	0	10	10	10



$n \times n$ image

*

1	0	-1
1	0	-1
1	0	-1



1	0	-1
1	0	-1
1	0	-1



$f \times f$ filter

=

0	30	30	0
0	30	30	0
0	30	30	0
0	30	30	0



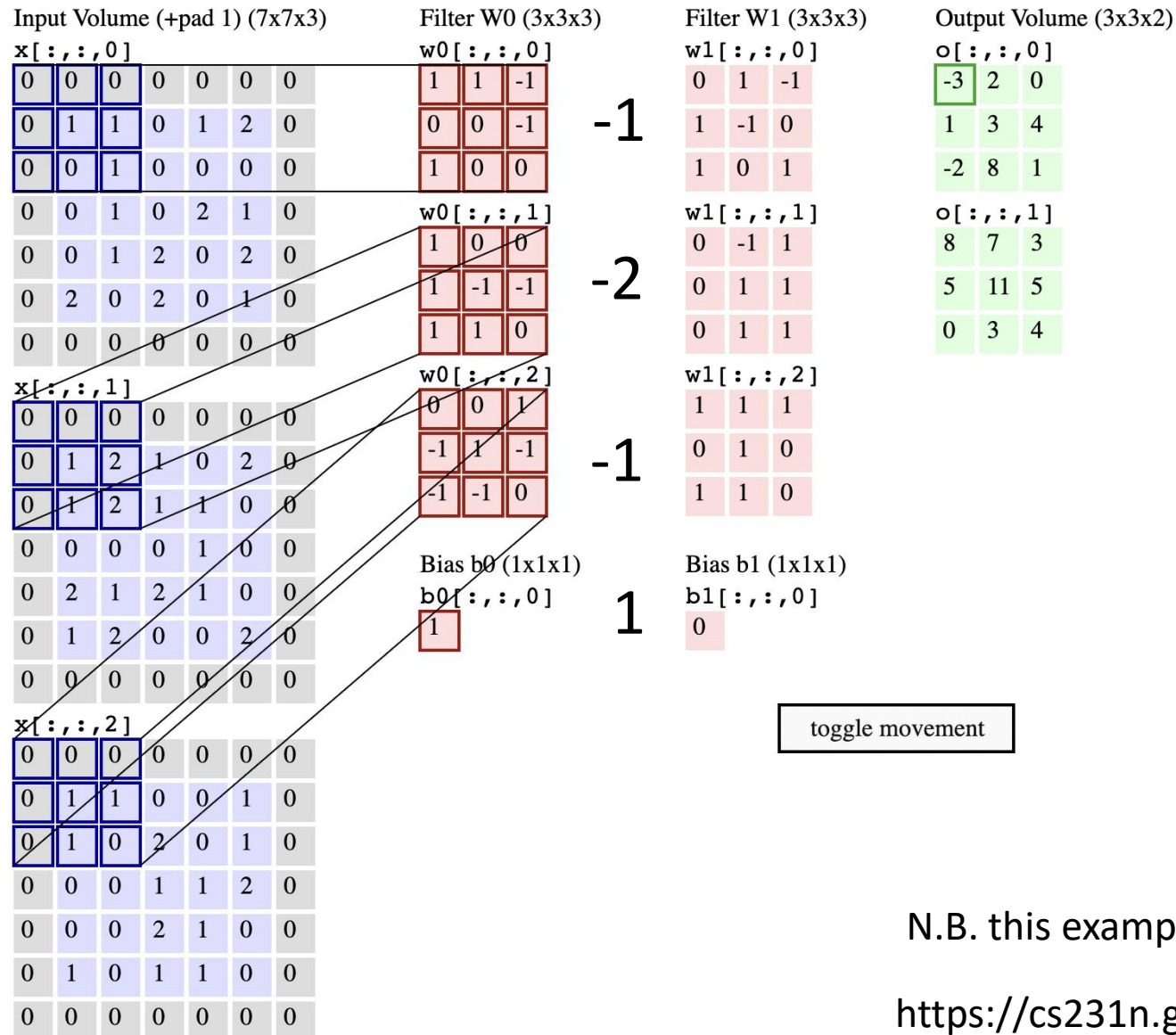
=

0	-30	-30	0
0	-30	-30	0
0	-30	-30	0
0	-30	-30	0



out = $n - f + 1$

Convolution Layer (CONV)



Hyperparameters:

- Filter size
- Number of filter sets (channels)
- Padding
- Stride

toggle movement

N.B. this example the **stride = 2**, **padding = 1**, **channels = 2**

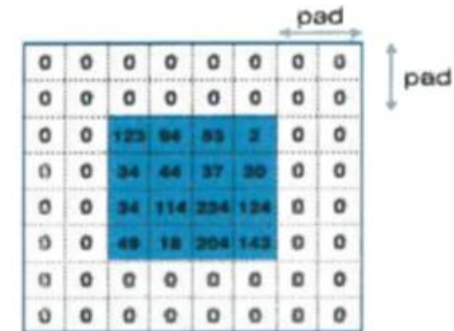
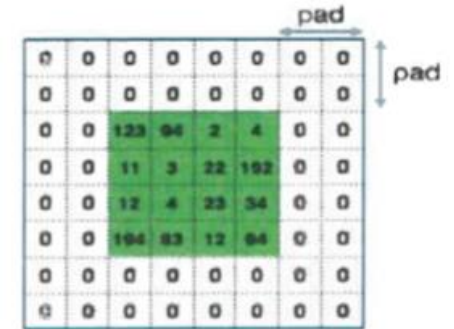
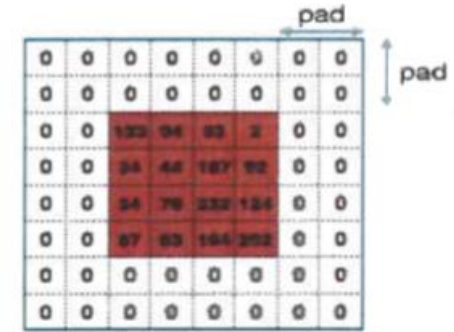
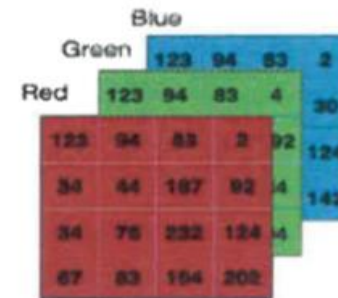
<https://cs231n.github.io/convolutional-networks/>

Padding

Adds zeros around the border of an image



=

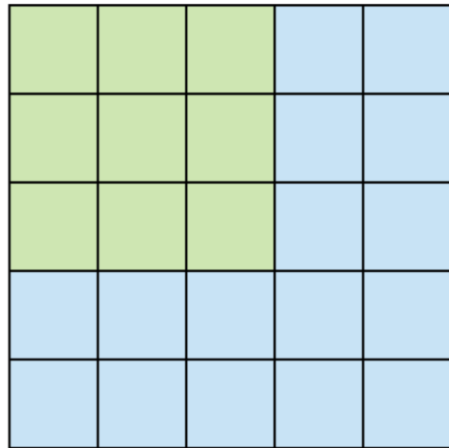


Use cases :

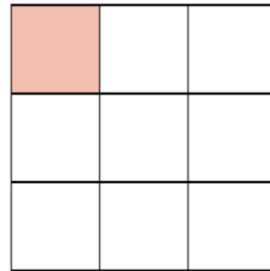
- Keeps more information at the border of an image
- Allows to *use a CONV layer without shrinking* the height and width of the volumes (important for deeper networks)

Strided convolutions

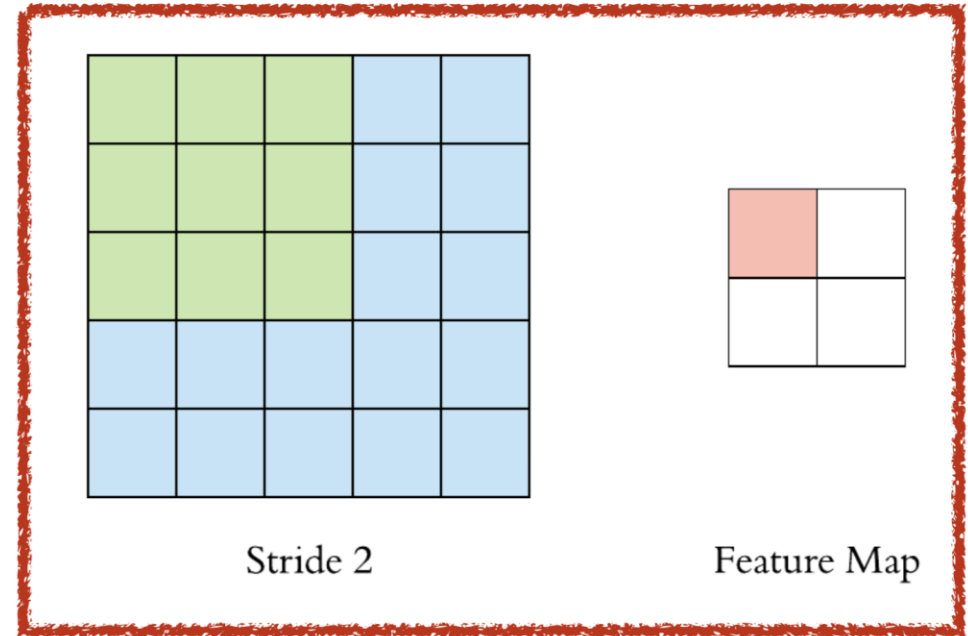
By how much you move the filter



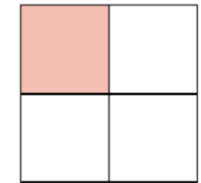
Stride 1



Feature Map



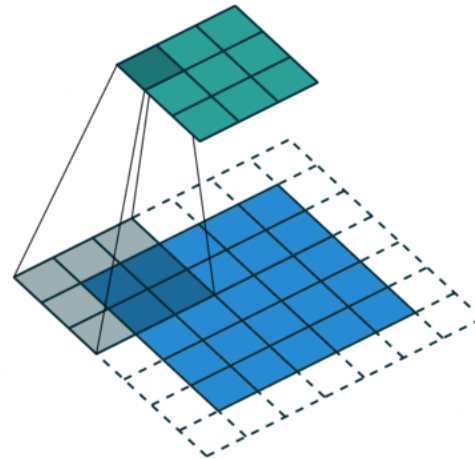
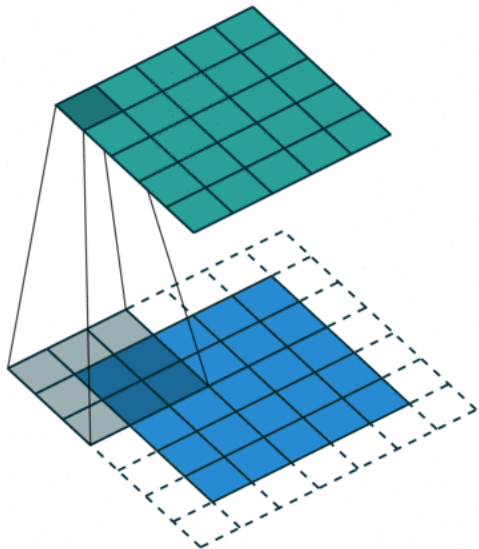
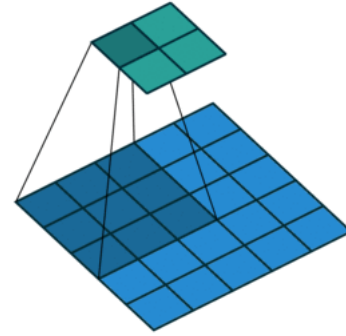
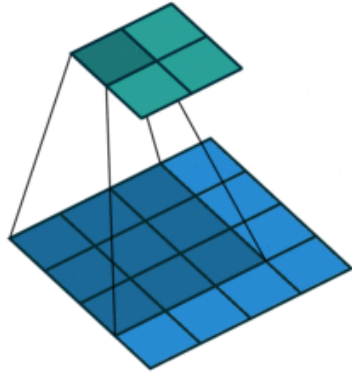
Stride 2



Feature Map

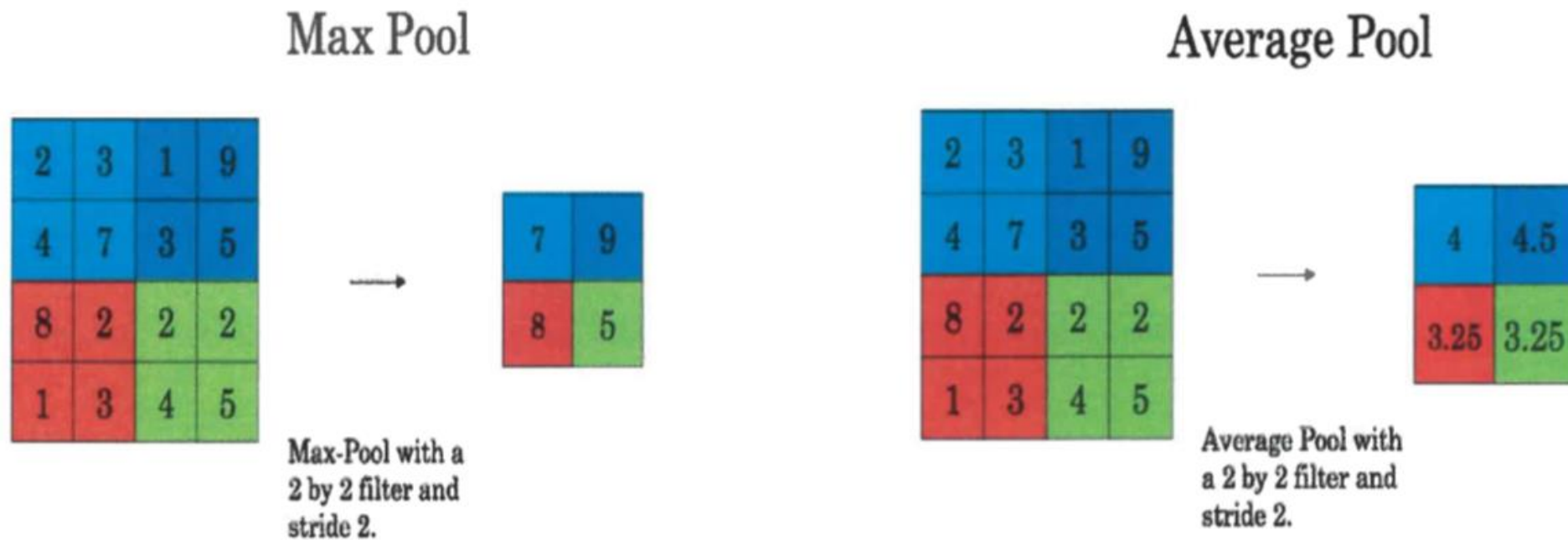
increasing stride from 1 to 2

Illustration



Pooling Layer (POOL)

- reduces the spatial dimension (n_H and n_W) to **decrease computational power**



Get the max value

Get the average value

One Look Is Worth A Thousand Words--

One look at our line of Republic, Firestone, Miller and United States tires can tell you more than a hundred personal letters or advertisements.

WE WILL PROVE THEIR VALUE
BEFORE YOU INVEST ONE DOLLAR
IN THEM.

Ever consider buying Supplies from a catalog?

What's the use! Call and see what you are buying. One look at our display of automobile and motorcycle accessories will convince you of the fact.

THAT WE HAVE EVERYTHING FOR
THE AUTO

Piqua Auto Supply House

133 N. Main St.—Piqua, O.

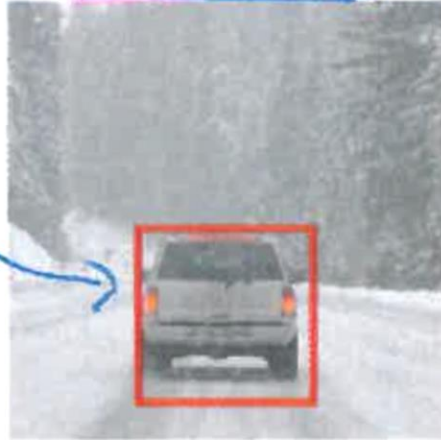
Object Detection

Image classification



"Car"

Classification with localization



"Car"

Detection

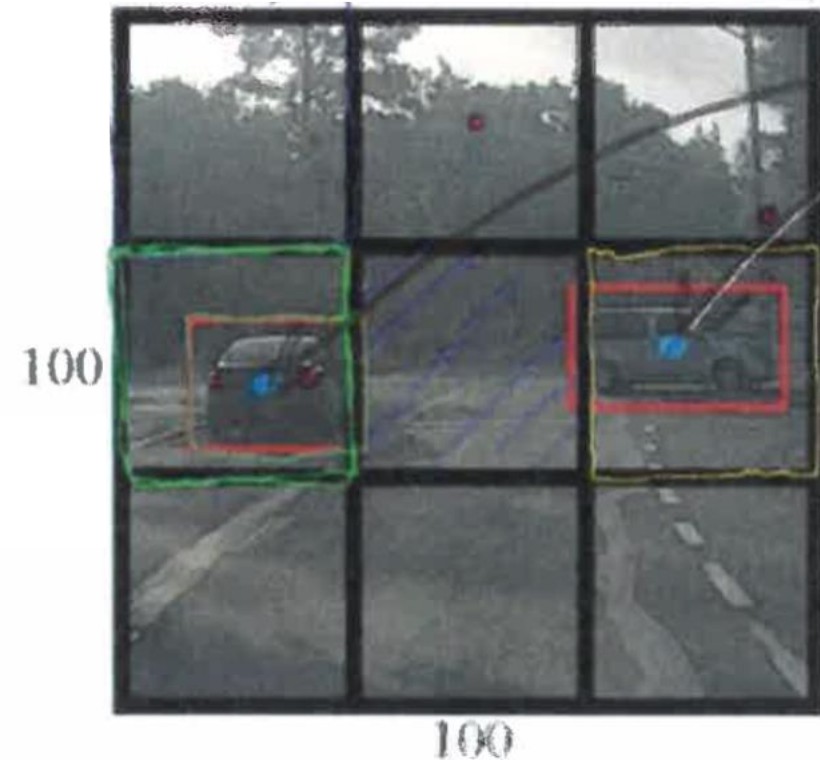
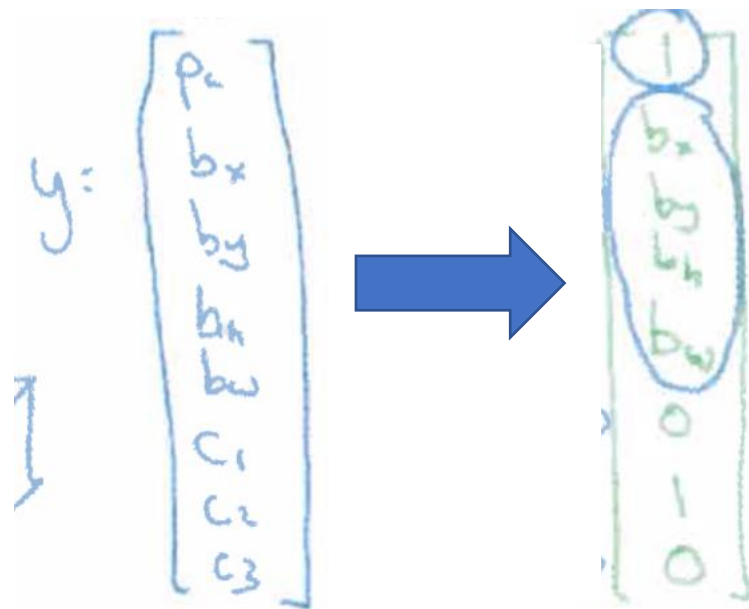


multiple objects

1 object

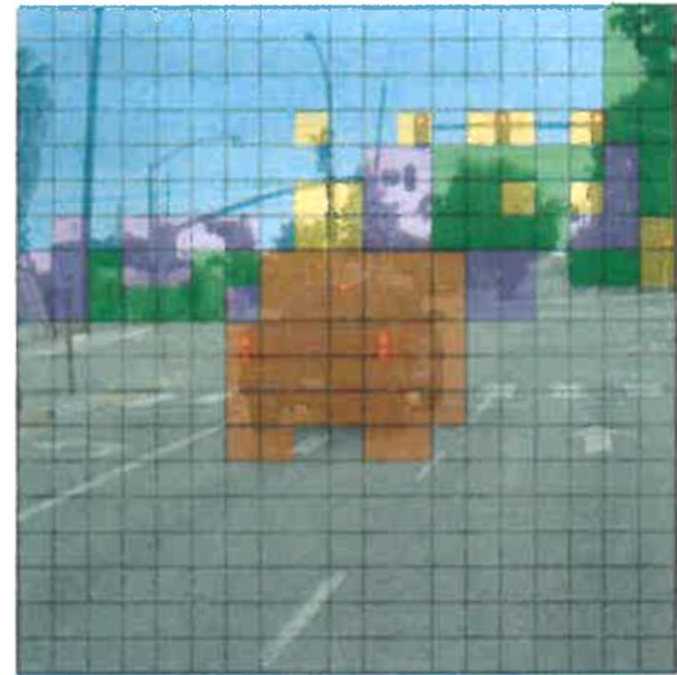
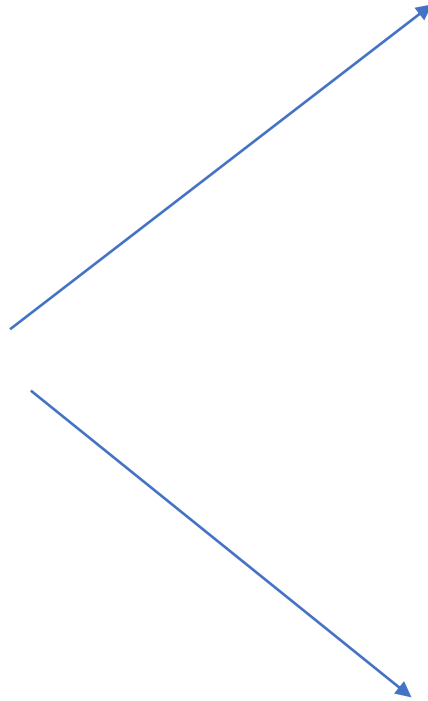
Yolo (*YOu Look only Once*)

- define a **grid** in the image
- apply the training to each cell (need ground-truth bounding boxes)
- For each 'anchor box' and 3 classes we have:



- Allows for overlapping objects

YOLO prediction visualisation



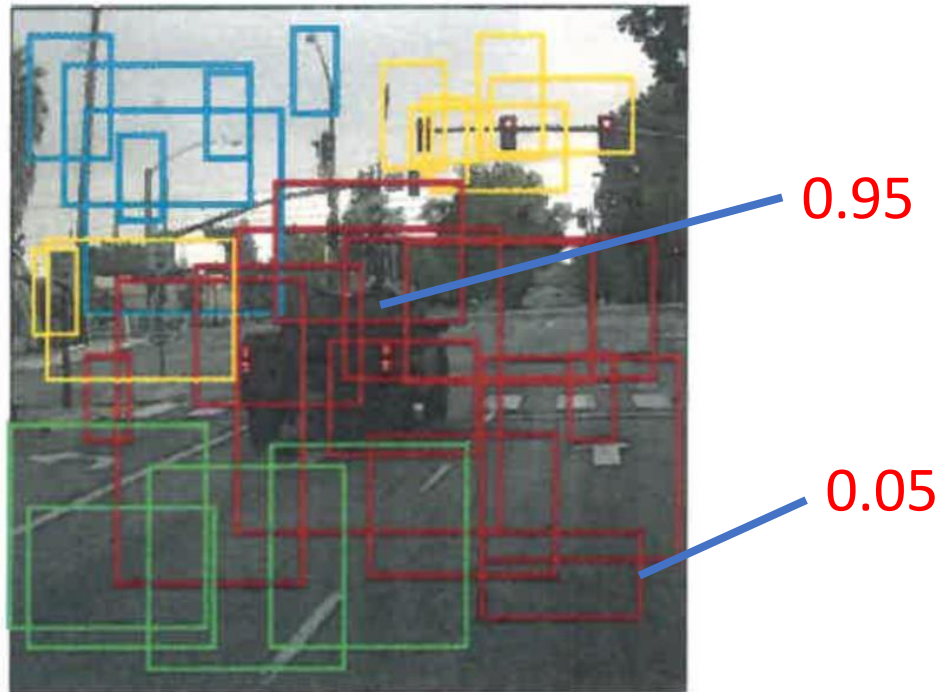
- car
- road sign
- tree
- traffic light
- sky
- background

- Filter the boxes using :
 - 1) score thresholding
 - 2) non-max suppression



Score Thresholding

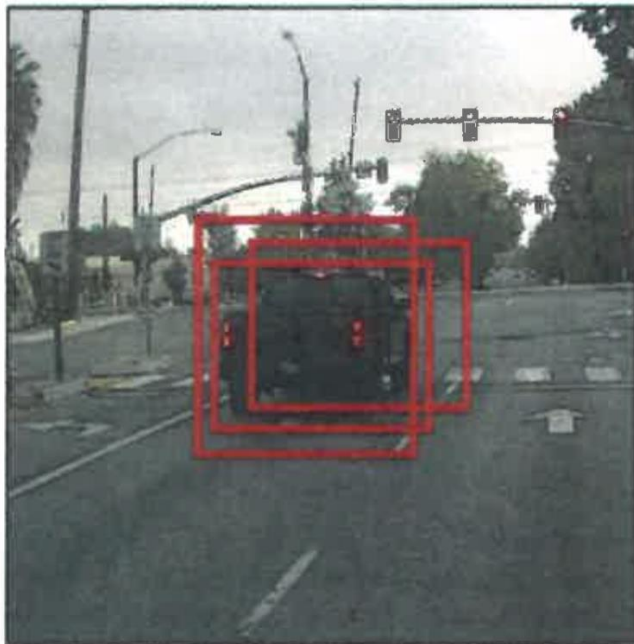
- Throw away boxes that have detected a class with a score less than the threshold (*0.6 for example*)



Non-max suppression

- ensures that an object is detected **only once**
 - Choice based on the p_c value : *keep the largest p_c output* and *discard any remaining box with $IoU > 0.5$*

Before non-max suppression



Non-Max
Suppression



After non-max suppression



Intersection Over Union (IOU)

- performance metric on how similar two boxes are with each other
- (higher the better!)

Outcome of the algorithm



True bounding box

$$\text{IoU} = \frac{\text{Size of } \begin{array}{c} \text{yellow hatched box} \\ \text{green hatched box} \end{array}}{\text{Size of } \begin{array}{c} \text{yellow hatched box} \\ \text{green hatched box} \end{array}}$$

Intersection Over Union (IOU)



Yellow = intersection I
Green = union U

$$\text{IoU} = I/U$$

Can express this as:

$$\text{TP} / (\text{TP} + \text{FN} + \text{FP})$$

[see also, Jaccard Index]

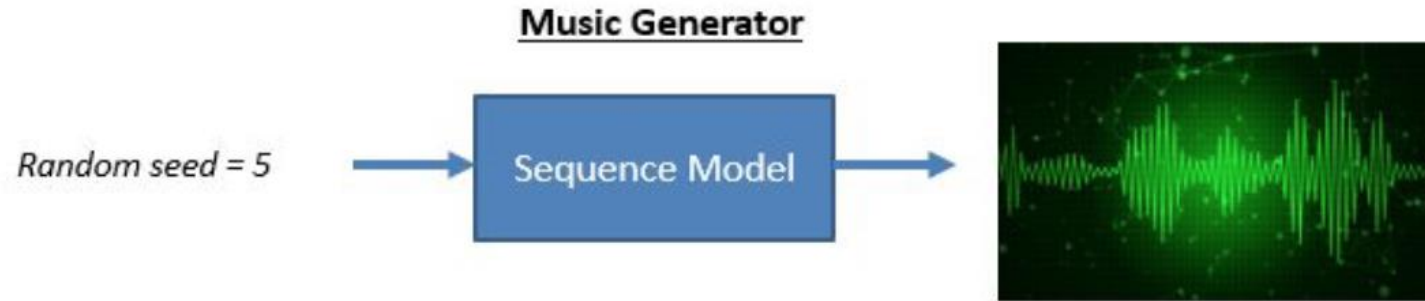
Generative Models

Holy grail of Deep Learning these days

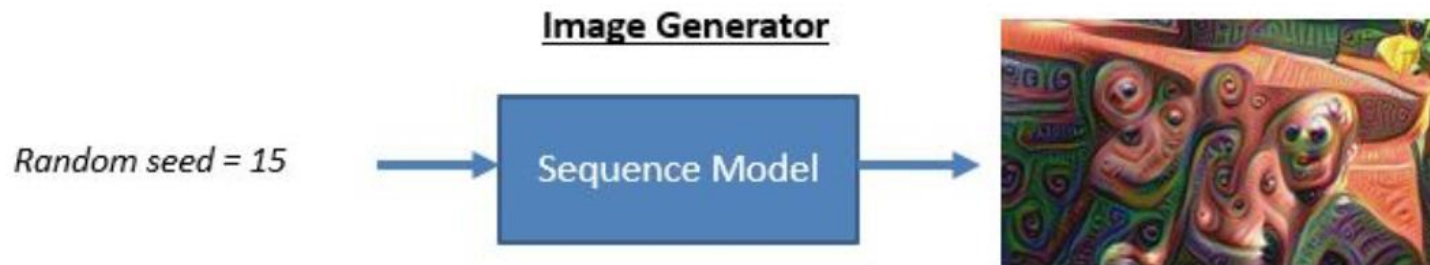
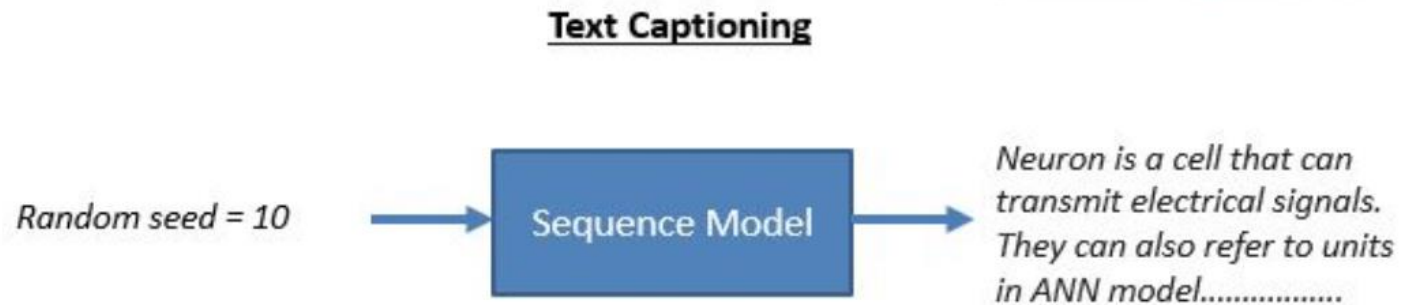


DALL-E : 'A photograph of a cow on the moon.'

Generative Models Examples

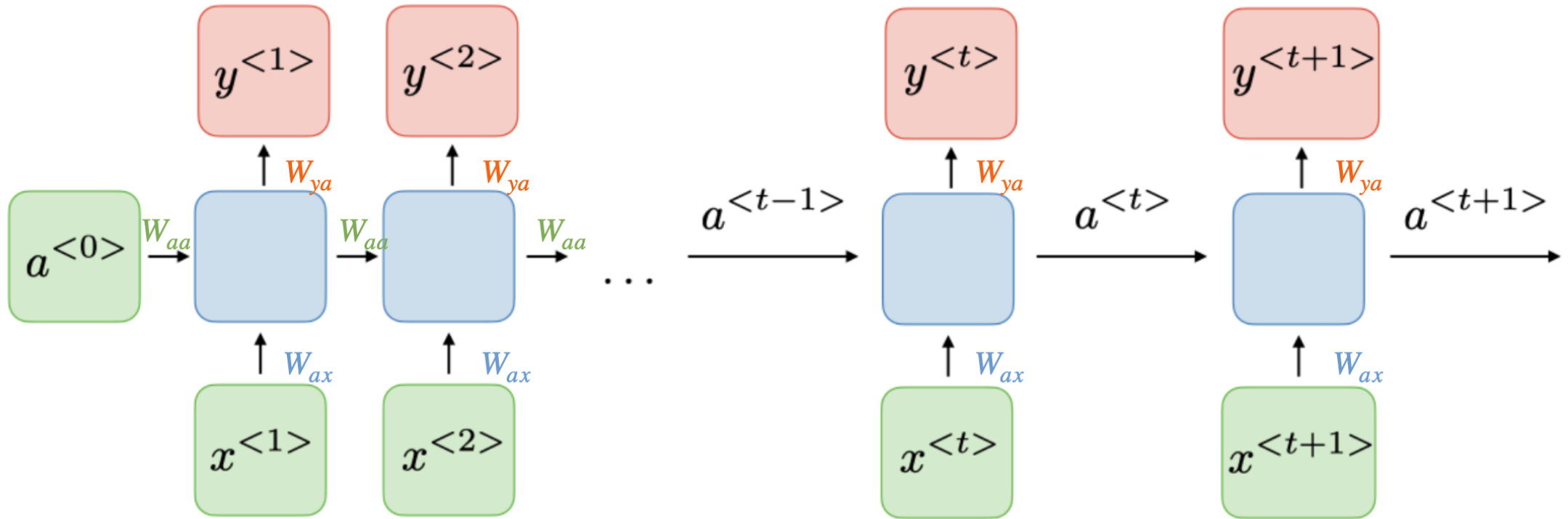


[DeepBach](#)



[GauGAN](#)

RNN model

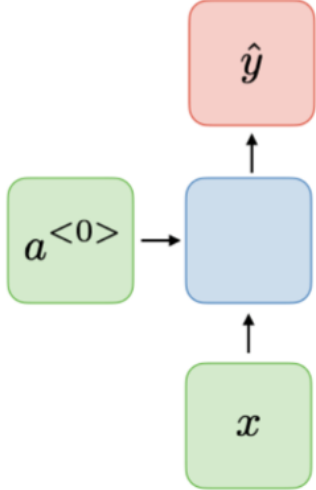


$$a^{<t>} = g_1(W_{aa}a^{<t-1>} + W_{ax}x^{<t>} + b_a)$$

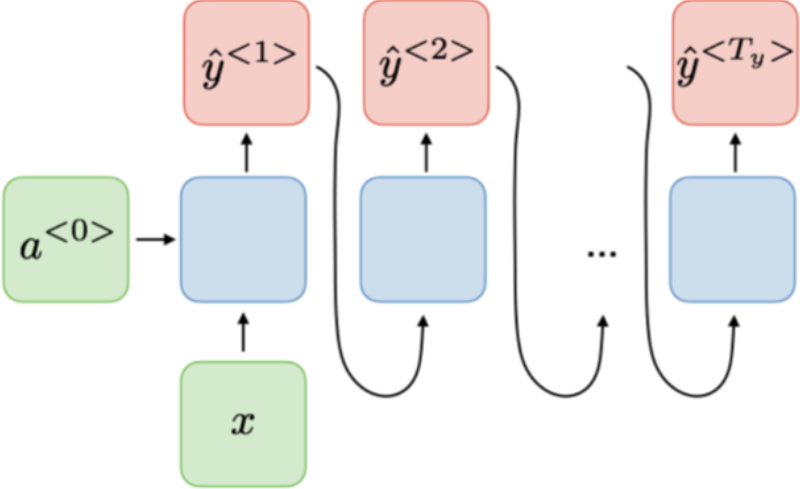
$$y^{<t>} = g_2(W_{ya}a^{<t>} + b_y)$$

$W_{ax}, W_{aa}, W_{ya}, b_a$ and b_y are weights that are shared temporally and g_1, g_2 activation functions

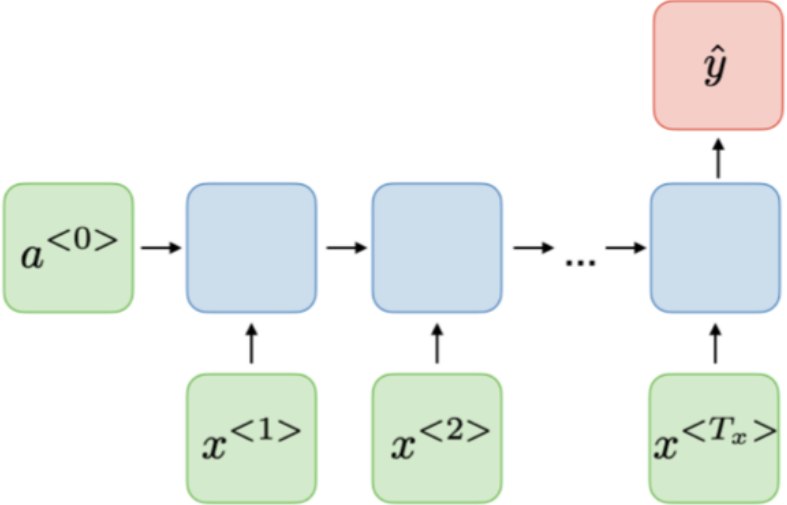
Applications of RNN

Type of RNN	Illustration	Example
One-to-one $T_x = T_y = 1$		Traditional neural network

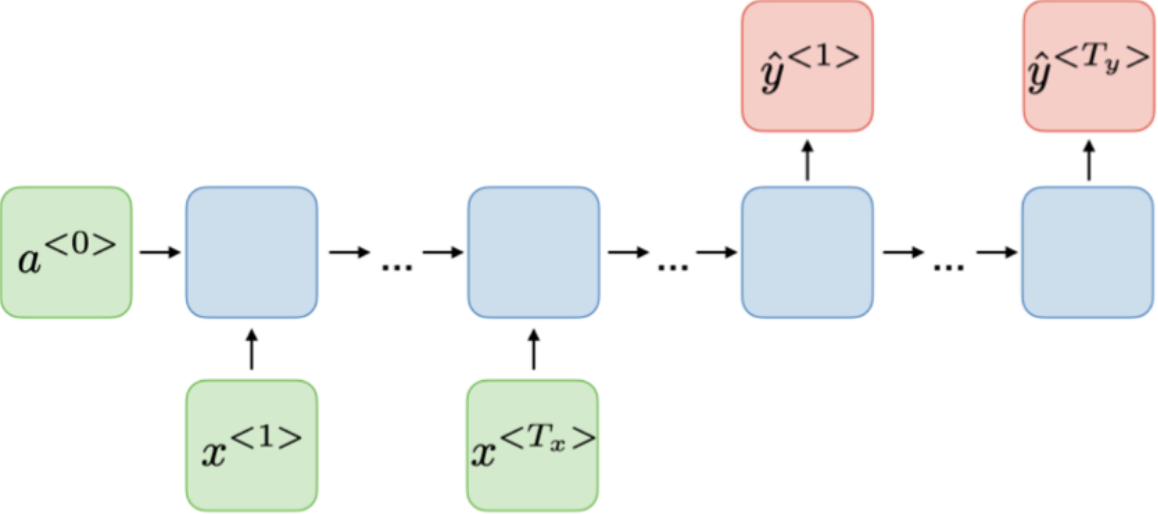
Applications of RNN

Type of RNN	Illustration	Example
One-to-many $T_x = 1, T_y > 1$	 <p>The diagram illustrates a one-to-many RNN architecture. It shows a sequence of hidden states (blue boxes) connected by curved arrows. The first hidden state receives an initial hidden state $a^{<0>}$ (green box) and an input x (green box). Each hidden state produces an output $\hat{y}^{<1>}$, $\hat{y}^{<2>}$, ..., $\hat{y}^{<T_y>}$ (red boxes). The output of one hidden state is fed into the next hidden state.</p>	Music generation

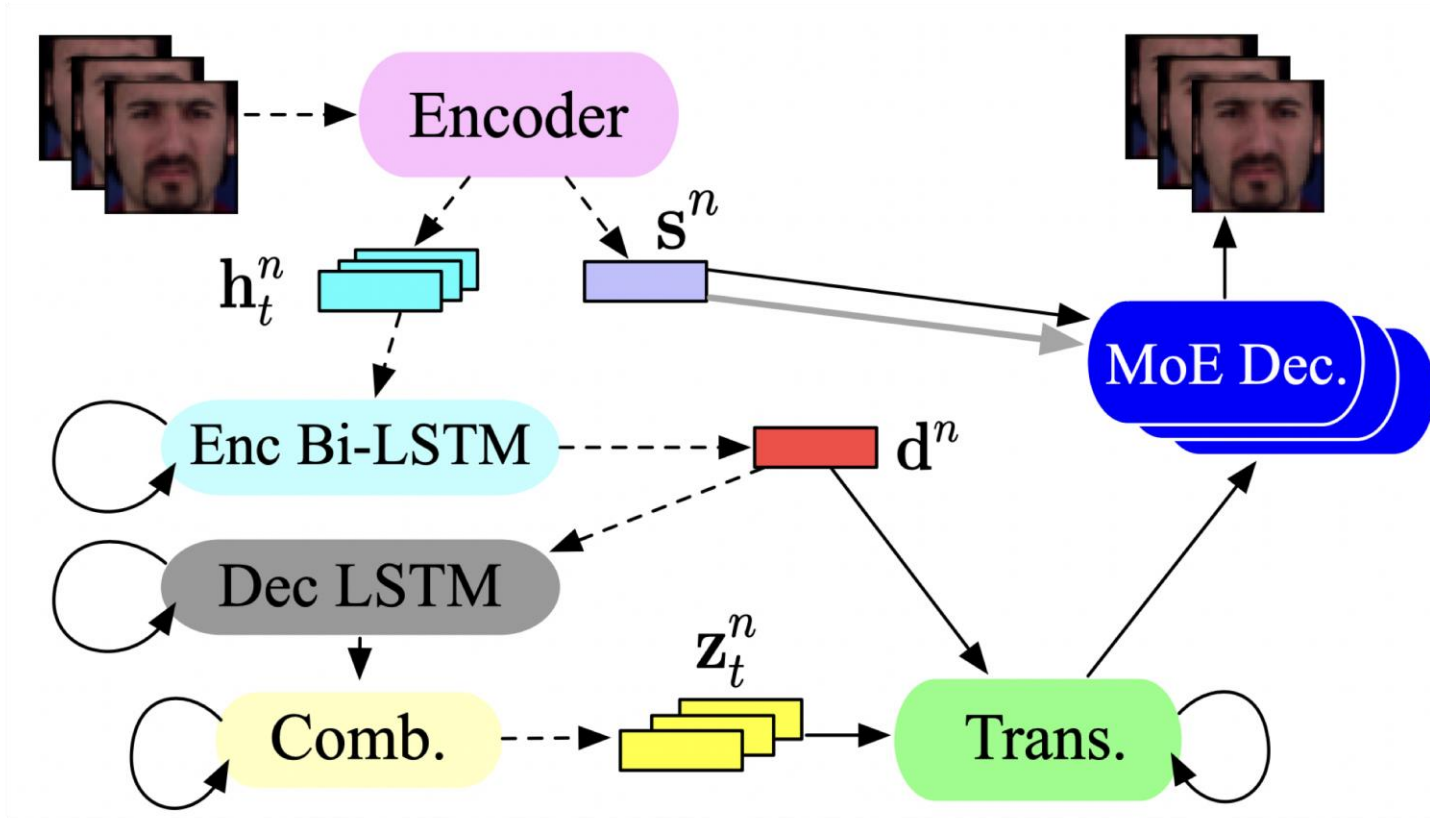
Applications of RNN

Type of RNN	Illustration	Example
Many-to-one $T_x > 1, T_y = 1$	 <p>The diagram illustrates a Many-to-one RNN architecture. It shows a sequence of input boxes labeled $x^{<1>}$, $x^{<2>}$, and $x^{<T_x>}$ feeding into a sequence of hidden state boxes. The final hidden state feeds into an output box labeled \hat{y}.</p>	Sentiment classification

Applications of RNN

Type of RNN	Illustration	Example
Many-to-many $T_x \neq T_y$		Machine translation

VDSM



n

Individual

t

Video Frame

d^n

Action Performed

s^n

Identity

z_t^n

Per-Frame Pose

h_t^n

Per-image embedding

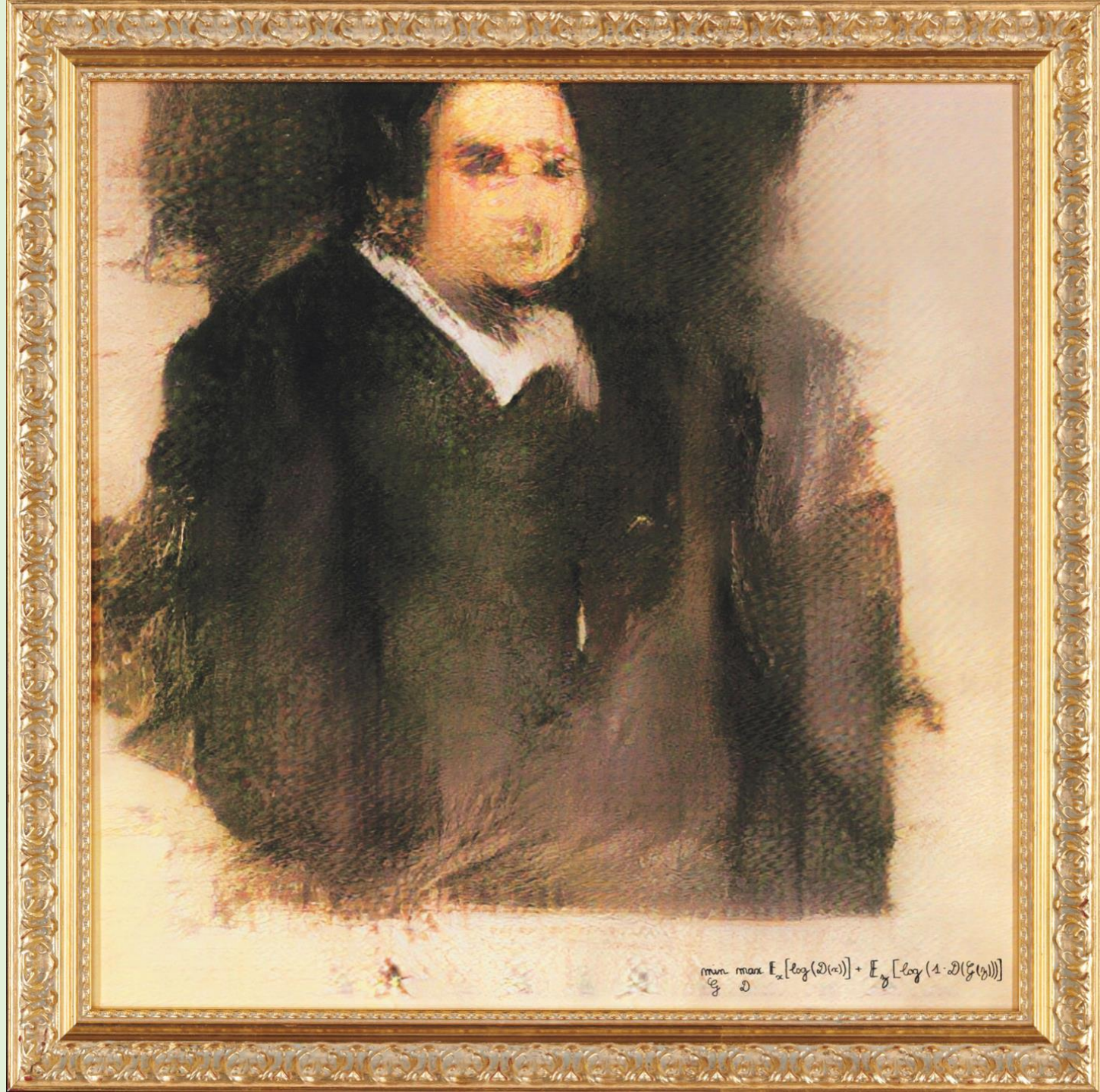
x

Generative Adversarial Network

Invented by Ian Goodfellow

*How much are you
ready to pay for it ?*

Christie's New York 2018



$$\min_G \max_D E_x [\log(\mathcal{D}(x))] + E_y [\log(1 - \mathcal{D}(G(y)))]$$

Principle

GENERATOR
"The Artist"
A neural network trying to create pictures of cats that look real.



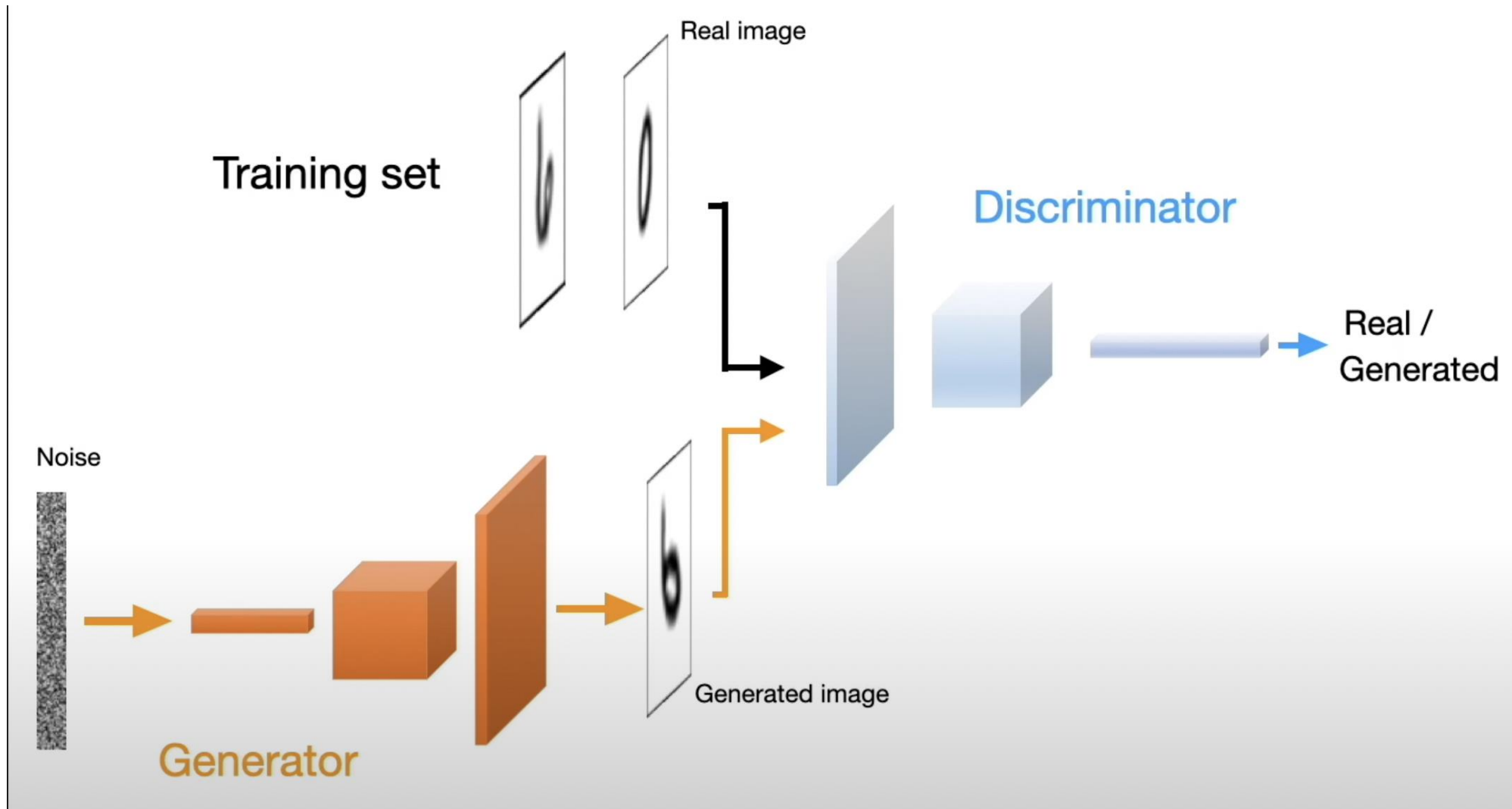
DISCRIMINATOR
"The Art Critic"
A neural network examining cat pictures to determine if they're real or fake.



Thousands of real-world images labeled "CAT"



Principle



Principle

Step 1: Train Discriminator and 'Freeze' Generator parameters

Step 2: Train Generator and 'Freeze' Discriminator parameters

$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_{\mathbf{z}}(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))]$$

Principle

Step 1: Train Discriminator and 'Freeze' Generator parameters

Step 2: Train Generator and 'Freeze' Discriminator parameters

$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_{\mathbf{z}}(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))]$$

Discriminator gradient for update (gradient ascent):

predict well on real images
=> want probability close to 1

predict well on fake images
=> want probability close to 0

$$\nabla_{\mathbf{w}_D} \frac{1}{n} \sum_{i=1}^n \left[\overbrace{\log D(\mathbf{x}^{(i)})} + \log \left(1 - \overbrace{D(G(\mathbf{z}^{(i)}))} \right) \right]$$

Principle

Step 1: Train Discriminator and 'Freeze' Generator parameters

Step 2: Train Generator and 'Freeze' Discriminator parameters

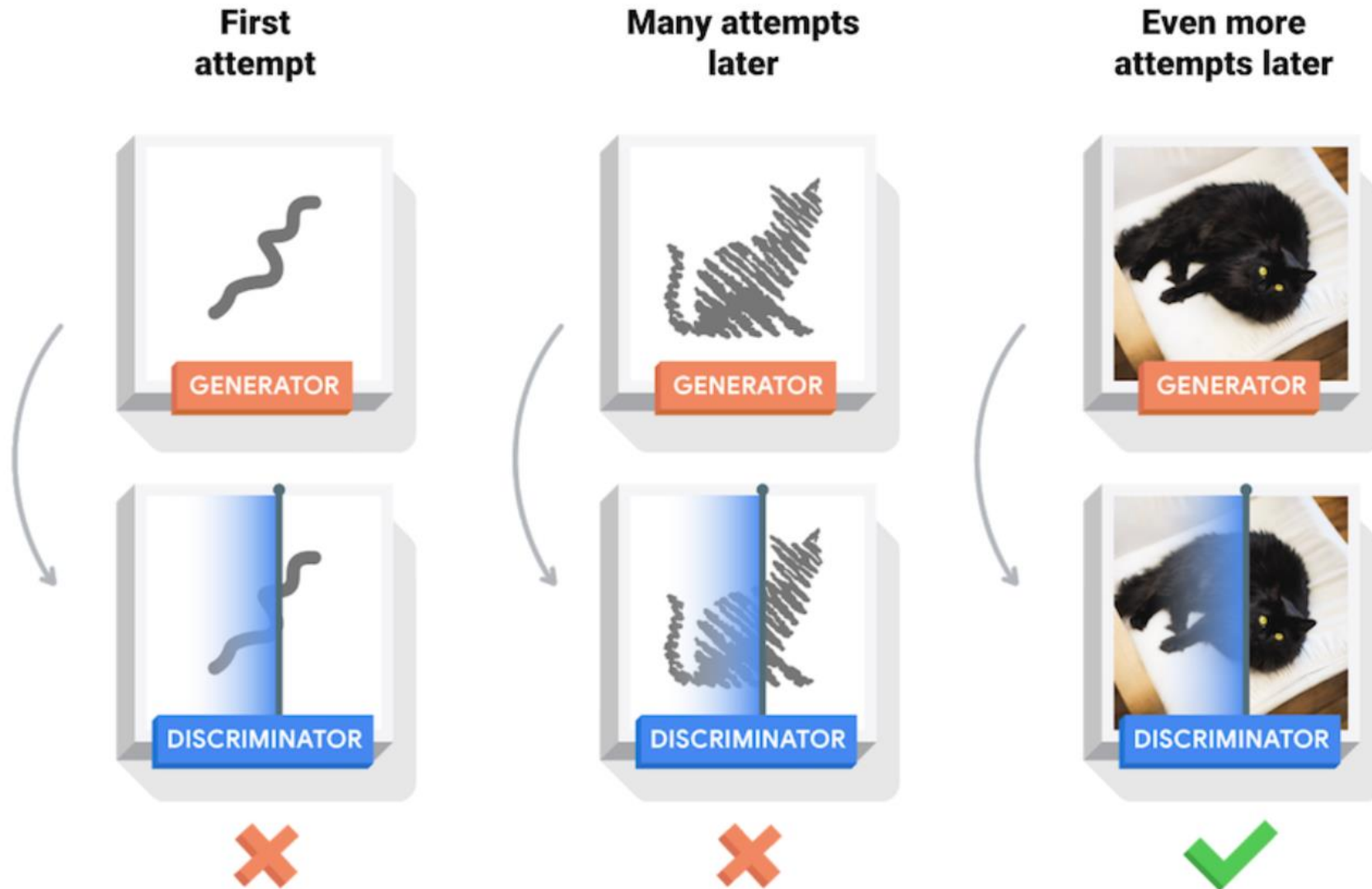
$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_{\mathbf{z}}(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))]$$

Generator gradient for update (gradient descent):

predict badly on fake images
=> want probability close to 1

$$\nabla_{\mathbf{w}_G} \frac{1}{n} \sum_{i=1}^n \log \left(1 - \overbrace{D \left(G \left(\mathbf{z}^{(i)} \right) \right)} \right)$$

Principle



GAN use case : generate images



Figure 3. Example results by our proposed StackGAN, GAWWN [20], and GAN-INT-CLS [22] conditioned on text descriptions from CUB test set. GAWWN and GAN-INT-CLS generate 16 images for each text description, respectively. We select the best one for each of them to compare with our StackGAN.

State Of The Art in GANs



(Karras et al, 2018)

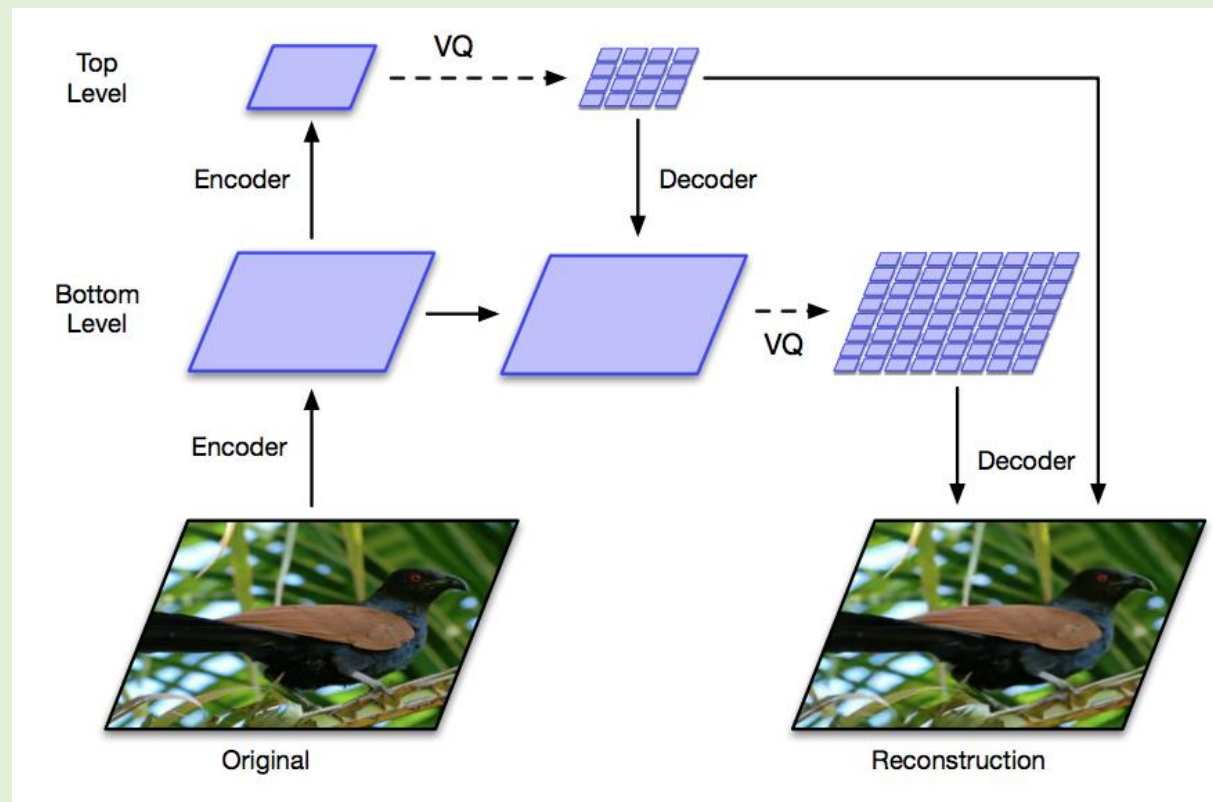


(Brock et al, 2018)

Adversarial Principles are Widely Applicable

- Fairness / Privacy Preservation
- Disentanglement

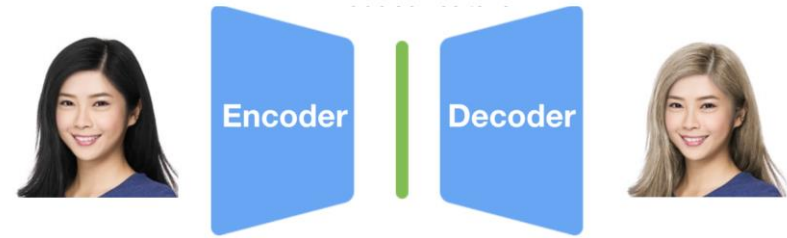
Variational AutoEncoder



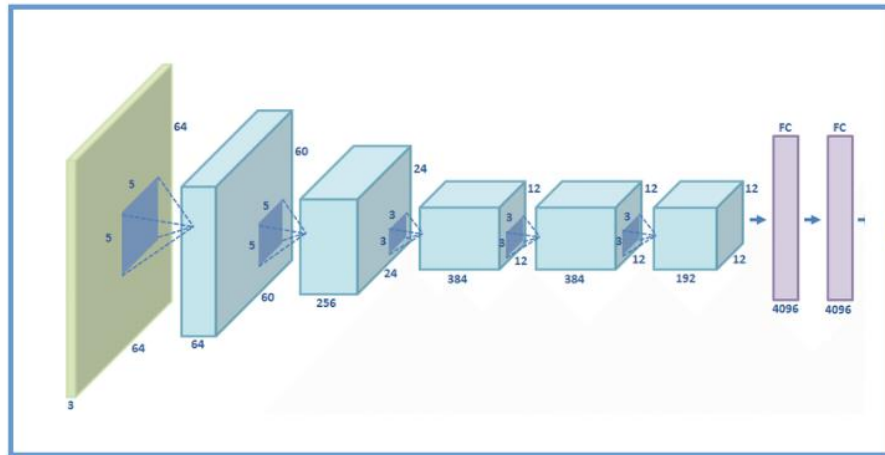
Principle AutoEncoder

Data Generation

- generate appropriately novel data



Input

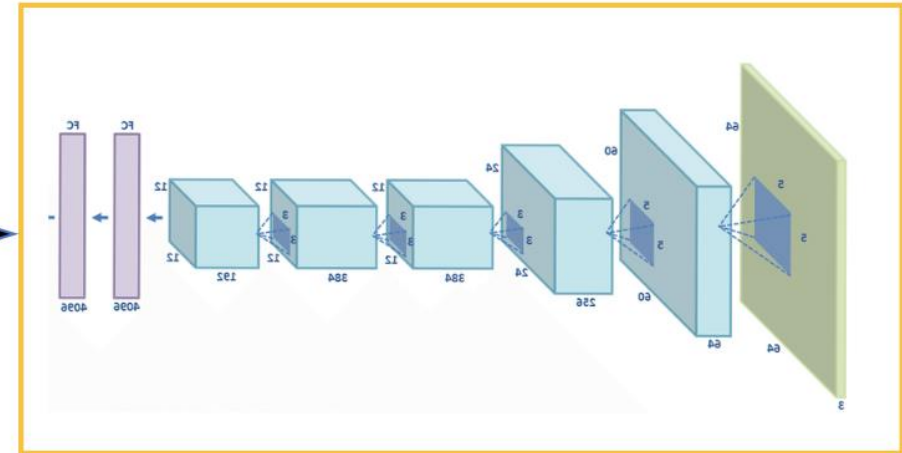


Encoder

Latent space/
Feature



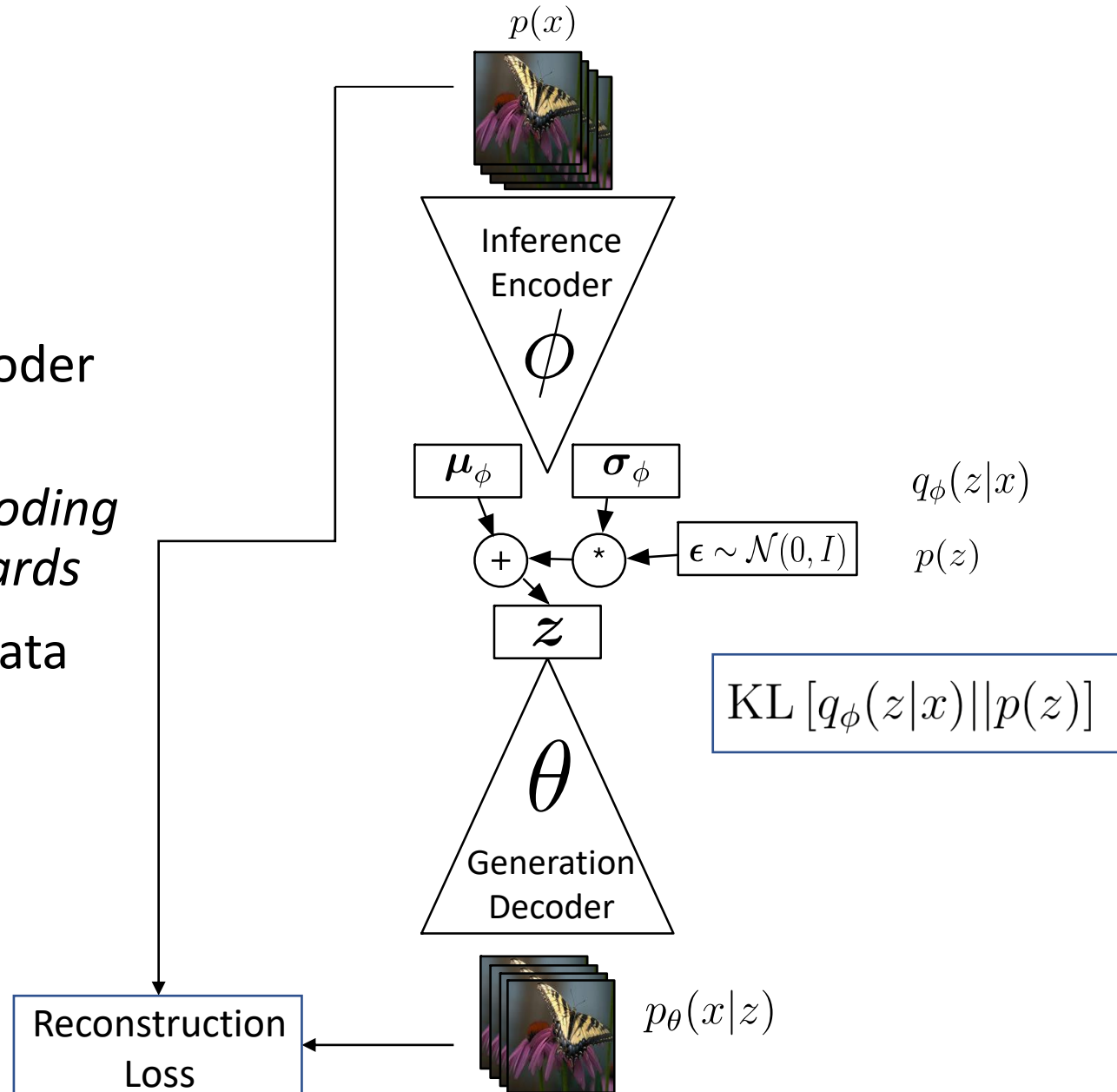
Reconstruction



Decoder

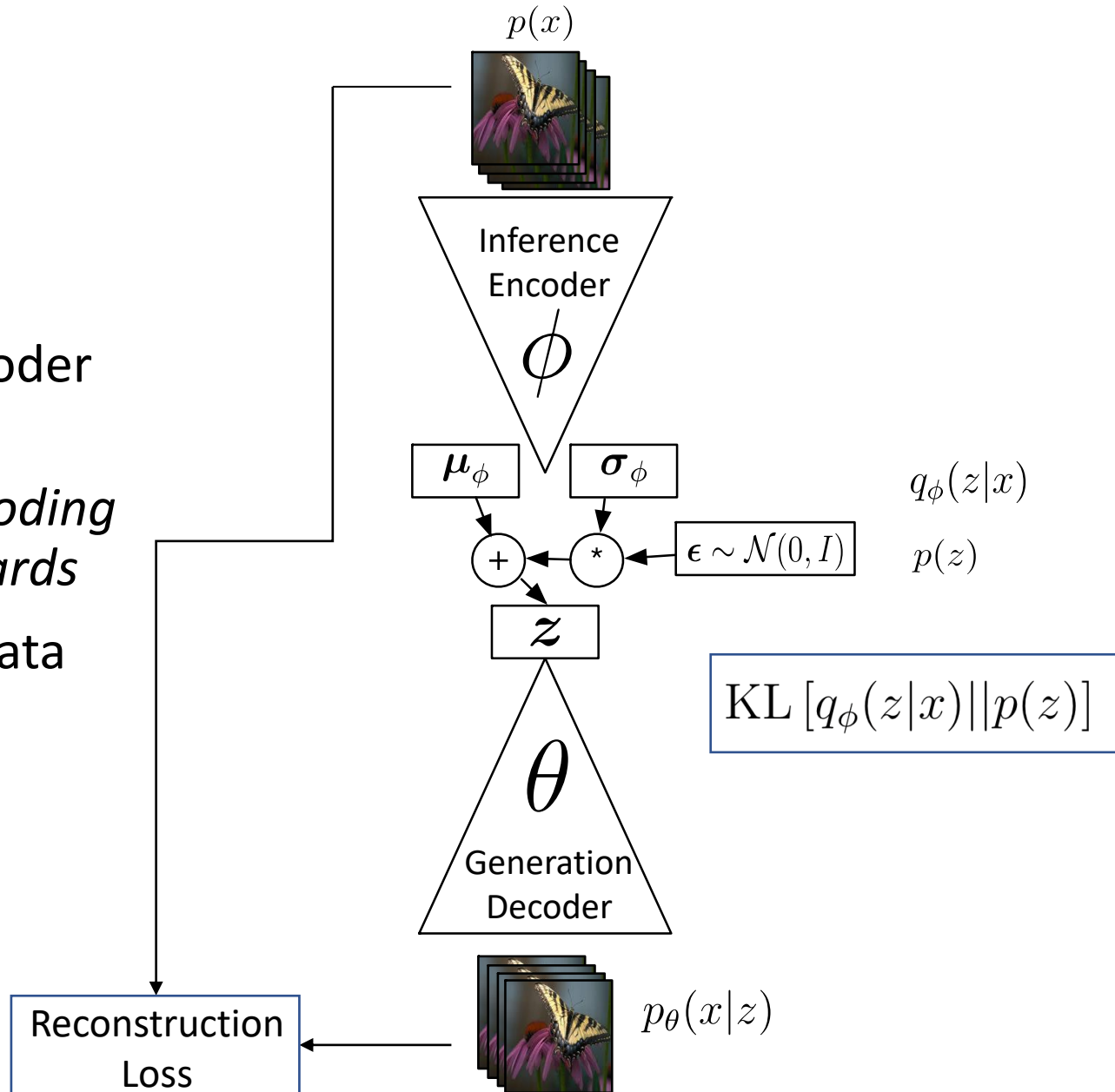
Principle

- Pass images/data in through encoder 'bottleneck'
- *Parameterize this bottleneck encoding so we can sample from it afterwards*
- Reconstruct the original image/data from the encoding



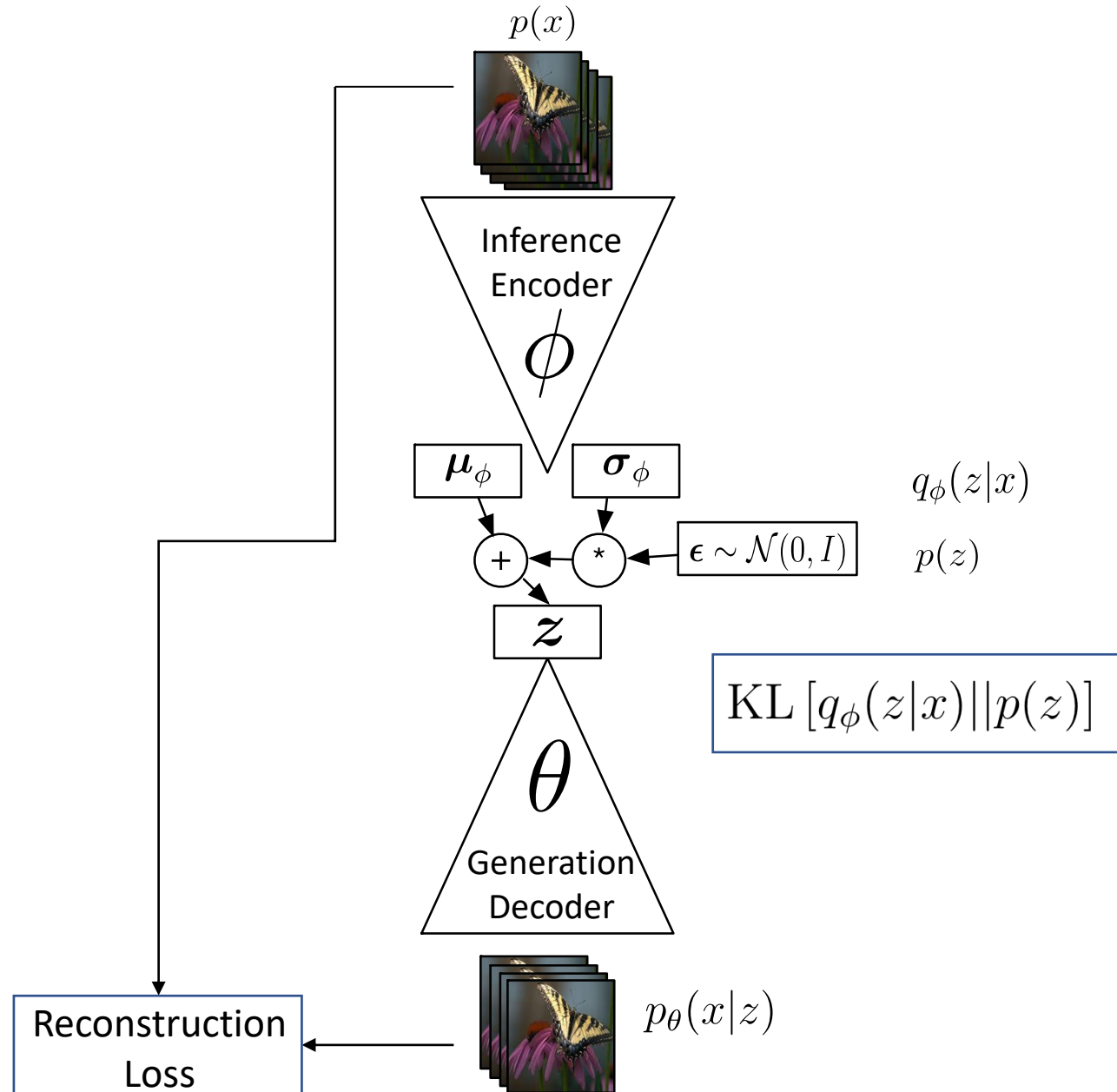
Principle

- Pass images/data in through encoder 'bottleneck'
- *Parameterize this bottleneck encoding so we can sample from it afterwards*
- Reconstruct the original image/data from the encoding

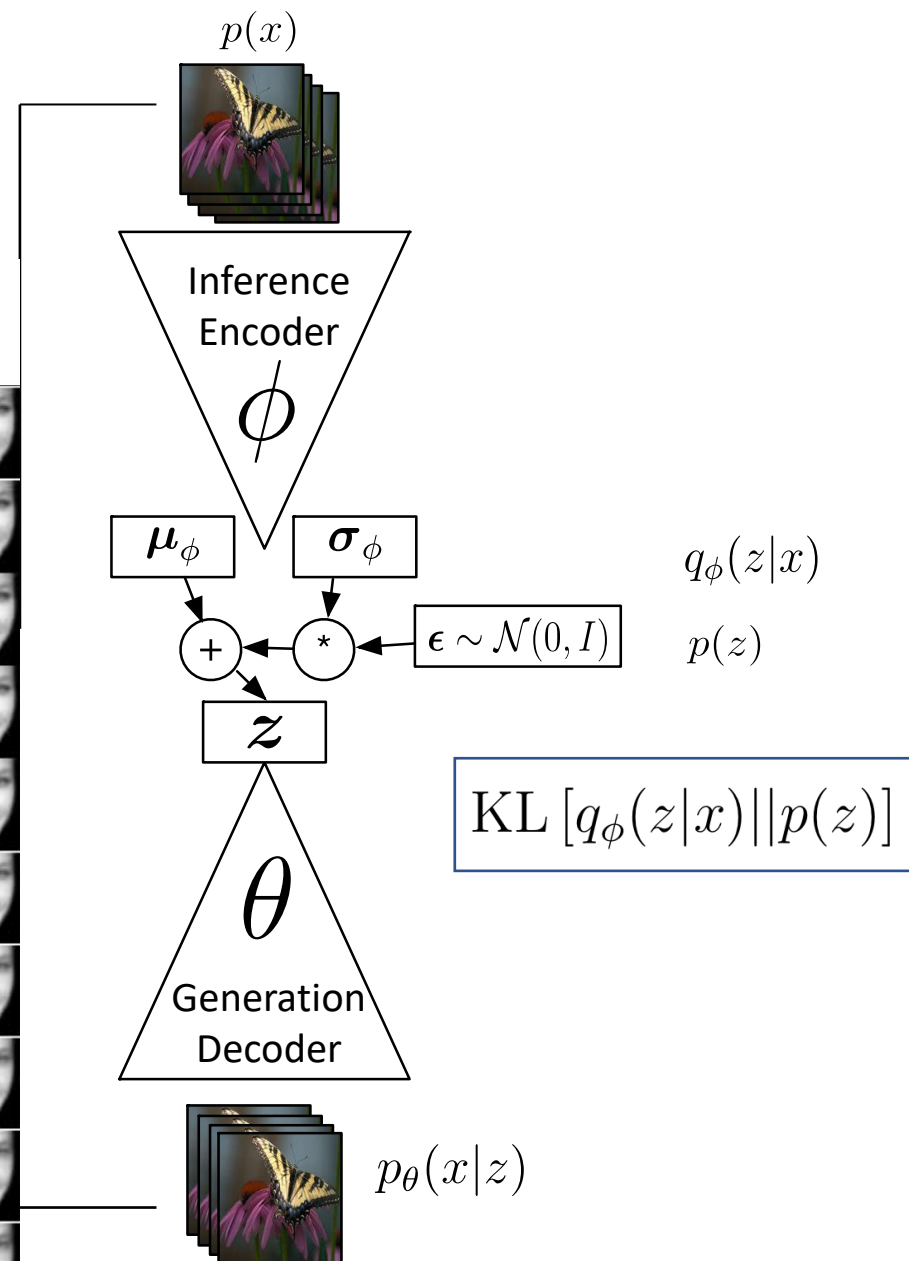
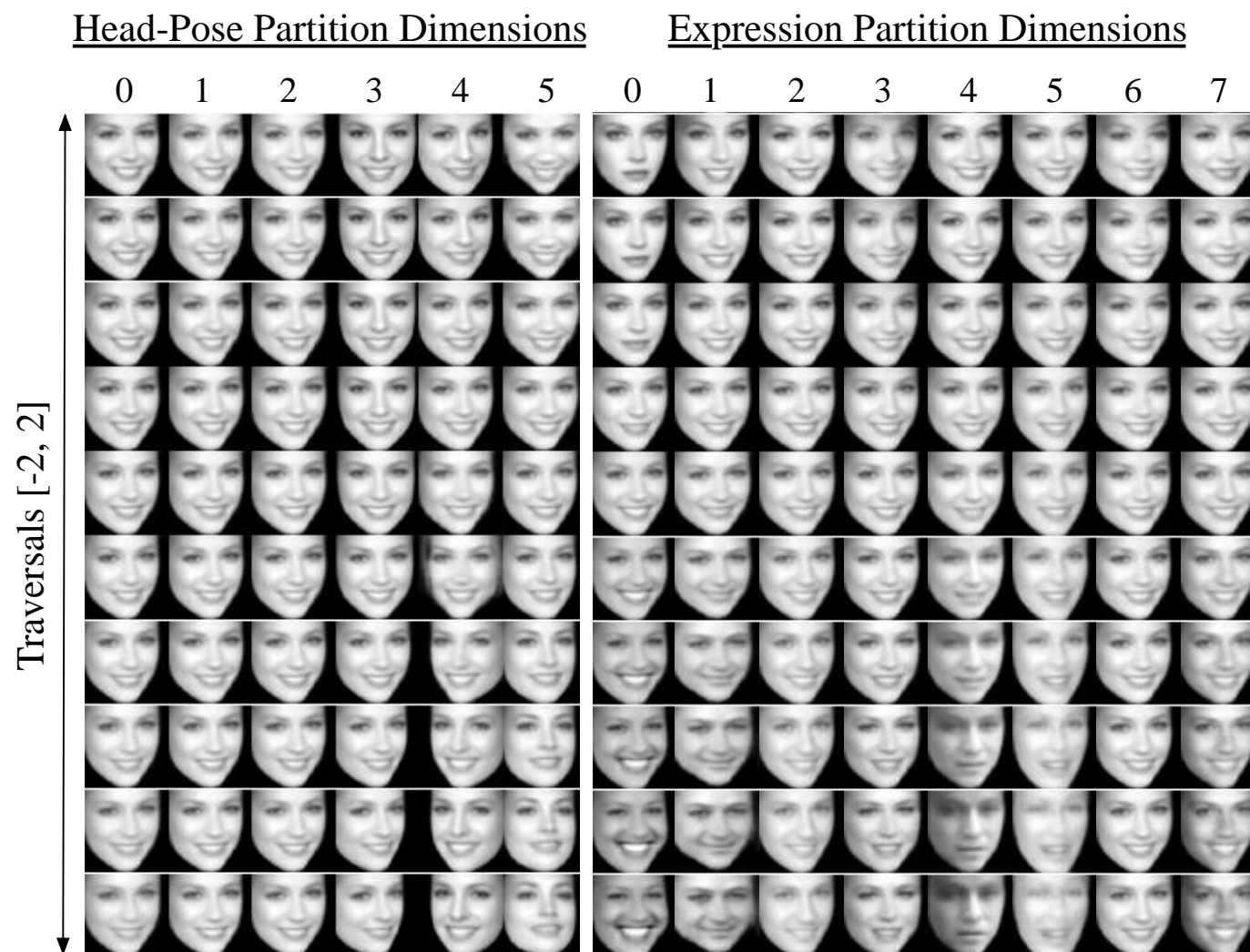


VAE use cases

- Compression
- Data generation
- Latent variable modeling
- Density estimation



VAE use cases



Tutorial / Practical

